



## Intel® Perceptual Computing SDK

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My First C++ Application



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## Introduction

The Intel® Perceptual Computing SDK is a library of pattern detection and recognition algorithm implementations exposed through standardized interfaces. The library's purpose is to lower barriers to using these algorithms and shift the application developers' focus from coding the algorithm details to innovating on the usage of these algorithms for next generation human computer experience.

Assuming that you have followed the **Getting Started** guide to install the SDK, we will go through the steps to create and run a simple C++ application using the SDK.

First, it's always a good habit to check if the camera and the SDK are installed correctly. Here are the steps:

- Launch the **capture\_viewer** application from the startup menu: **Startup**→**Intel® Perceptual Computing SDK**→**Tools**→**Capture Viewer**.
- Select a color stream, a depth stream and an audio stream from the **DepthSense 325 Audio/Video Capture** module.
- Select **Control**→**Display** to render the streams.

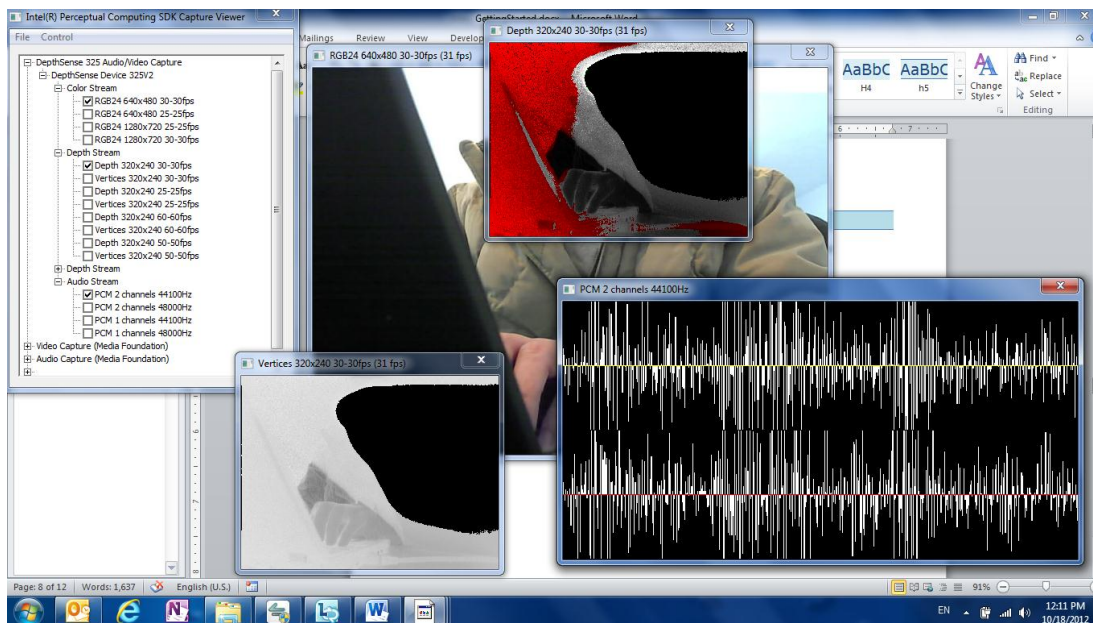
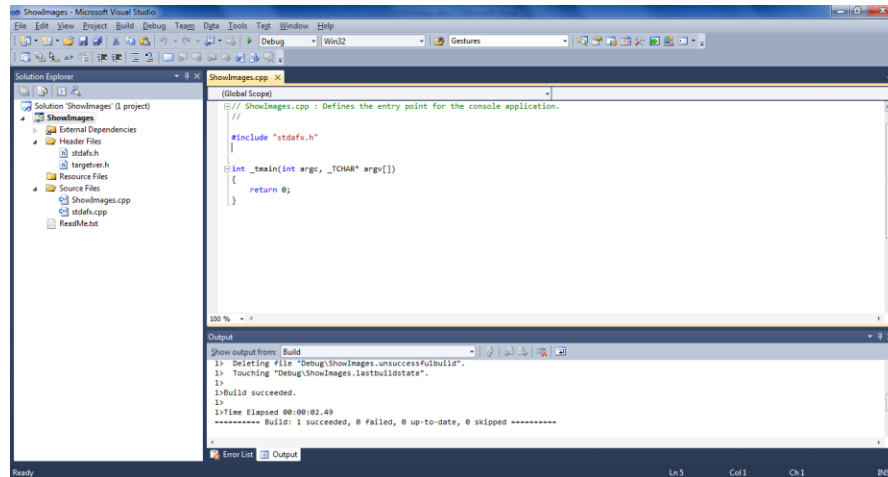


Figure 1: Camera Testing for Color, Depth and Audio

If your screen looks similar to the one shown in Figure 1, the camera is working as expected. It's time to create a simple application. To do something similar to the **capture\_viewer** application, we will develop an application that shows color and depth pictures.

# My First C++ Application

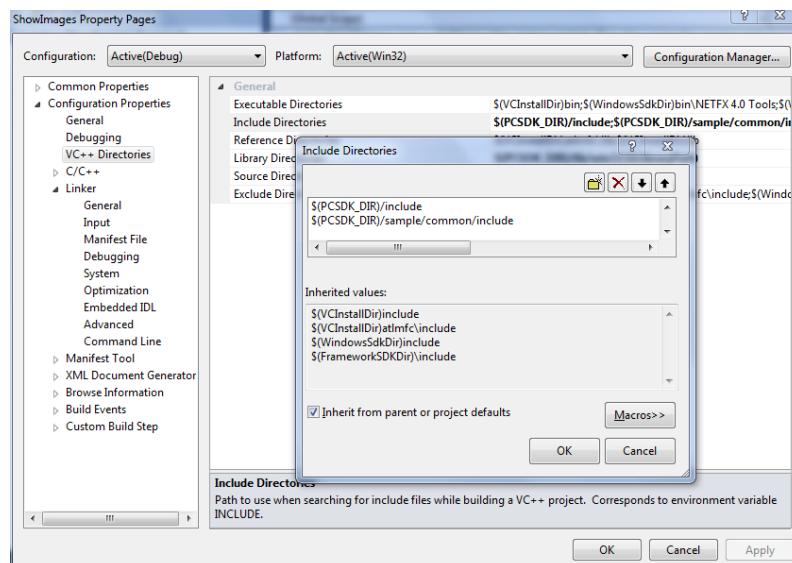
Launch Microsoft\* Visual Studio\* 2010. Create a new console application called `ShowImages` (see Figure 2).



**Figure 2: New Console Application**

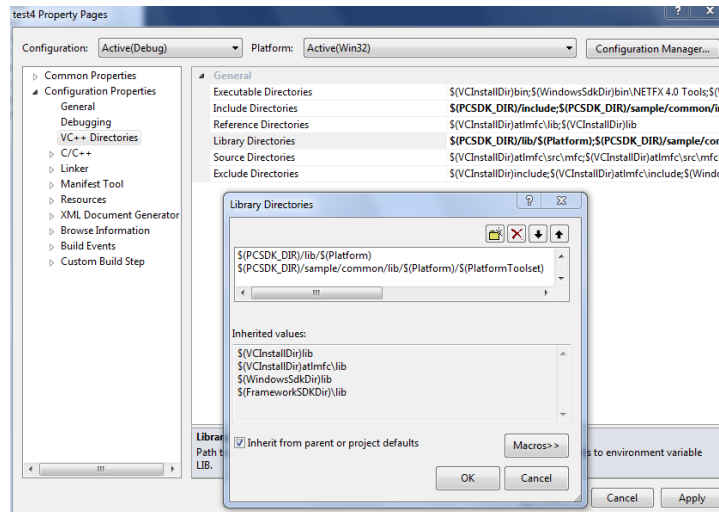
Add the SDK include files and library paths, as illustrated in Figure 3, Figure 4, and Figure 5, to the project so that the compiler and linker can find the SDK files as follows:

- Select **Project** → **Properties**, and then the **VC++ Directories** tab. Add `$(PCSDK_DIR)/include` to the include directories, as illustrated in Figure 3. We will need to use some sample utilities. Add `$(PCSDK_DIR)/sample/common/include` to the include directories as well.



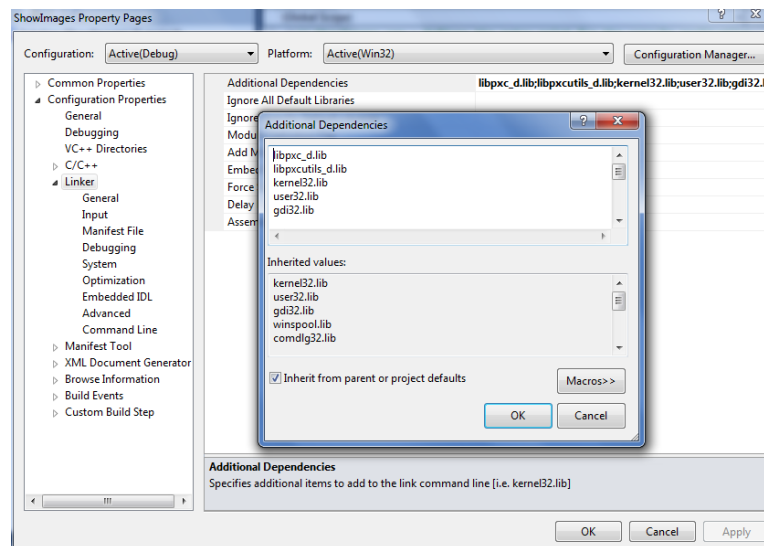
**Figure 3: SDK Application Project Include Settings**

- Add `$(PCSDK_DIR)/lib/$(PlatformName)` and `$(PCSDK_DIR)/sample/common/lib/$(PlatformName)/$(PlatformToolset)` to the library directories, as in Figure 4.



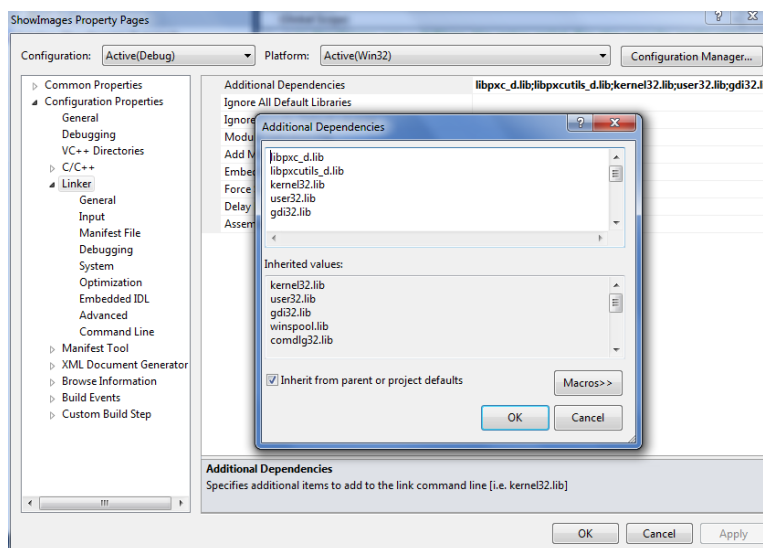
**Figure 4: SDK Application Project Library Path Settings**

- Go to the **Linker** → **Input** tab and add `libpxc_d.lib` and `libpxcutils_d.lib` (for the **Debug** build), or `libpxc.lib` and `libpxcutils.lib` (for the **Release** build) to the **Additional Dependencies** tab, as illustrated in Figure 5. Here `libpxc` is the SDK library code, and the `libpxcutils` is the sample utility library.



**Figure 5: SDK Application Project Library Settings**

- Go to the **C/C++** → **Code Optimization** tab and change the **Runtime Library** setting to be **Multi-Threaded Debug (/MTd)**, or **Multi-threaded (/MT)**, according to your project **Debug** or **Release** mode, as illustrated in Figure 6.



**Figure 6: SDK Application Code Optimization Settings**

For our first C++ SDK application (shown in Example 1), we are reading color pictures from the camera and rendering them.

```
#include "stdafx.h"
#include "util_render.h"
#include "util_pipeline.h"

int _tmain(int argc, _TCHAR* argv[]) {
    UtilPipeline pipeline;
    pipeline.EnableImage(PXCImage::COLOR_FORMAT_RGB32);
    pipeline.Init();
    UtilRender color_render(L"Color Stream");
    for (;;) {
        if (!pipeline.AcquireFrame(true)) break;
        PXCImage *color_image=pipeline.QueryImage(PXCImage::IMAGE_TYPE_COLOR);
        if (!color_render.RenderFrame(color_image)) break;
        pipeline.ReleaseFrame();
    }
    pipeline.Close();
    return 0;
}
```

**Example 1: Simple Image Capture Application**

The code uses the `UtilPipeline` utility classes. We first enable color image capturing by the `pipeline.EnableImage(PXCImage::COLOR_FORMAT_RGB32)` function, and then initialize the pipeline. In the for loop, the `AcquireFrame` function waits for a color sample to be available, then we render it using the `UtilRender::RenderFrame` function. We use the `ReleaseFrame` function to indicate that there are no more operations for the current frame. It's time to go read the next frame.

Run the code; you should see the color rendering window similar the one in in Figure 7. Click the close button on the top to close the application.



**Figure 7: The Sample Capture Application Render Window**

You may notice that the color window is of the default resolution. This is usually 640x480. To change to a different resolution, simply enter the resolution as part of the **EnableImage** function as illustrated in Figure 8. Compile and run it. The application will show a 720p resolution color window.

```
#include "stdafx.h"
#include "util_render.h"
#include "util_pipeline.h"

int _tmain(int argc, _TCHAR* argv[]) {
    UtilPipeline pipeline;
    pipeline.EnableImage(PXCImage::COLOR_FORMAT_RGB32, 1280, 720);
    pipeline.Init();
    UtilRender color_render(L"Color Stream");
    for (;;) {
        if (!pipeline.AcquireFrame(true)) break;
        PXCImage *color_image=pipeline.QueryImage(PXCImage::IMAGE_TYPE_COLOR);
        if (!color_render.RenderFrame(color_image)) break;
        pipeline.ReleaseFrame();
    }
    pipeline.Close();
    return 0;
}
```

**Figure 8: Simple Capture with An Explicit Resolution.**

Now, let's go one more step and add a depth stream in a different rendering window. It's easy to do. The code is shown in Figure 9.





```
#include "stdafx.h"
#include "util_render.h"
#include "util_pipeline.h"

int _tmain(int argc, _TCHAR* argv[])
{
    UtilPipeline pipeline;
    pipeline.EnableImage(PXCImage::COLOR_FORMAT_RGB32);
    pipeline.EnableImage(PXCImage::COLOR_FORMAT_DEPTH);
    pipeline.Init();
    UtilRender color_render(L"Color Stream");
    UtilRender depth_render(L"Depth Stream");
    for (;;) {
        if (!pipeline.AcquireFrame(true)) break;
        PXCImage *color_image=pipeline.QueryImage(PXCImage::IMAGE_TYPE_COLOR);
        PXCImage *depth_image=pipeline.QueryImage(PXCImage::IMAGE_TYPE_DEPTH);
        if (!color_render.RenderFrame(color_image)) break;
        if (!depth_render.RenderFrame(depth_image)) break;
        pipeline.ReleaseFrame();
    }
    pipeline.Close();
    return 0;
}
```

**Figure 9: Color and Depth Image Capture**

Compile and run it. You should see two windows as shown in Figure 10: one for the color stream and the other for the depth stream. Closing any of the color and depth windows will close the application.



**Figure 10: Color and Depth Image Capture Render Windows**